

QDD Lite

**Desktop Multi-axis Educational Robot** 

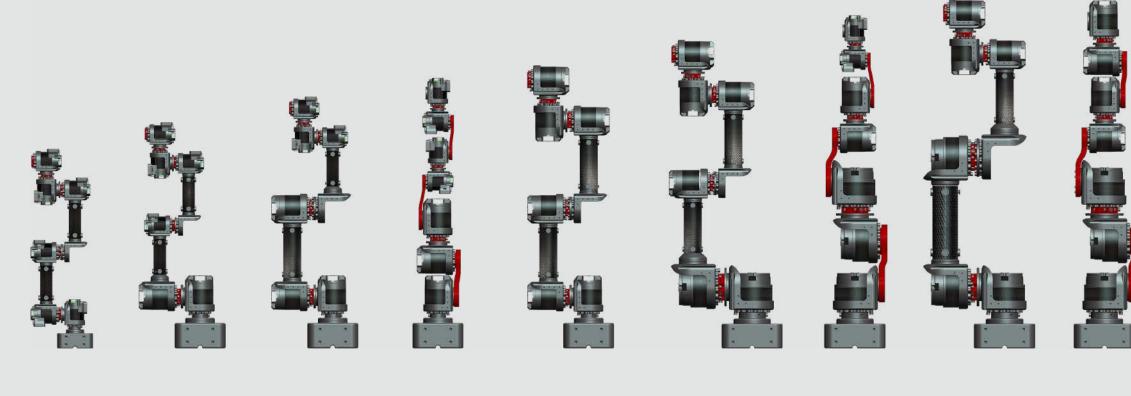
All joints are powered by SCA QDD Lite series.. It reaches up to 430mm with 500g end load. Due to the composite materials, the R&D cost of high-end robots is greatly reduced.Gluon is mainly used

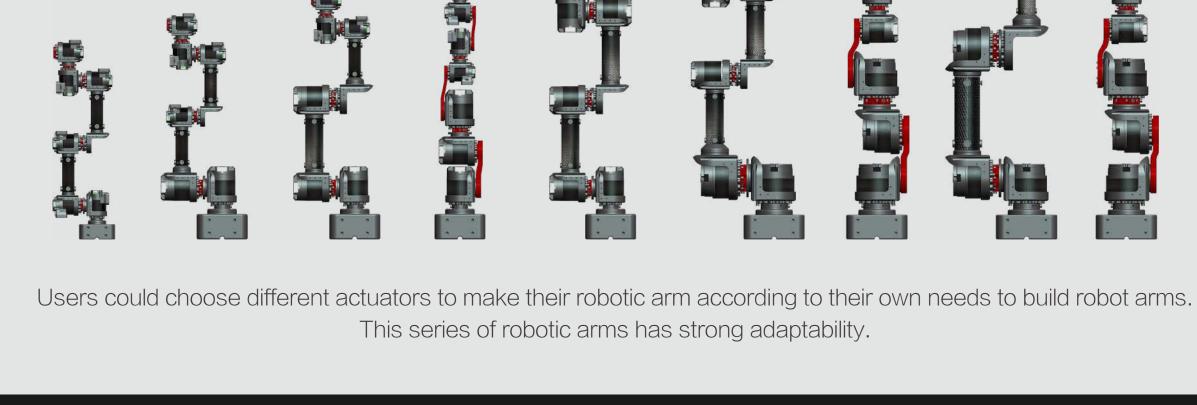
in education fields, including colleges, laboratories, research institutes, competitions, etc.





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## 3.7 [Kg]

**BASIC INFORMATION** 

Desktop 6-axis Gluon Parameters

Weight (without base) Weight (with base) 120 [W] 6 **Power Dissipation** Degree of freedom **IP54** 42 [v] Supply voltage Protection level 500 <sub>[g]</sub> **2** [mm] End load Repeatability 5~95 [%] 10~50<sub>[°]</sub> Operating temperature Working environment humidity For more information, please go to wiki.innfos.com

2.5 [Kg]

INFOS



### the software is installed and used. The IAS (INNFOS Actuator Studio) is the upper computer software for Gluon. For more information, please go to wiki.innfos.com.

Prepare accessories: one Gluon, ECB with the terminal resistor and the regenerative brake capac-

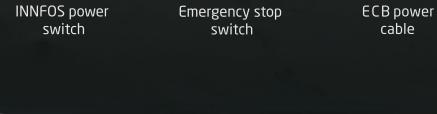
itor, the emergency stop switch + power supply, and a computer. After preparing the accessories,

HARDWARE AND SOFTWARE

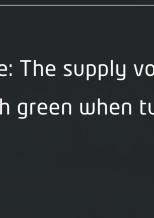
ACCESSORIES

Professional supporting products including ECB, ECB power cable, Controller module, make Gluon easier and

faster to use our products.



Connect SCA cable



(X=a[i]) 66X.03EEX

=new Array();

return x;)

=new Array();

ents; for(i=0; i=0

; d.MM\_p[j+].stc-a(s)s

"**))**>0**%parent\_r** 

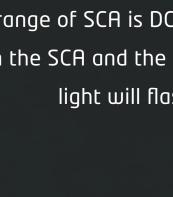
M sr=new Array, to the

j++]=x; if(|x.e5xc) \*\*\*\*\*\*

(x=a[i]) &&X. 05rc;1 -- X. 44

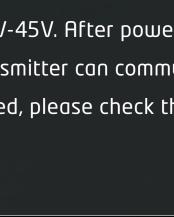
Connect ECB to

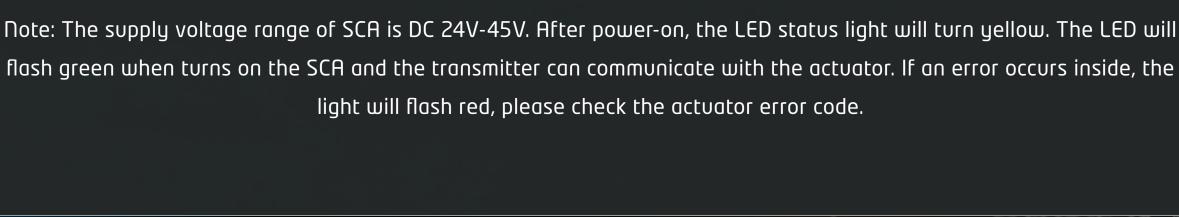
power supply

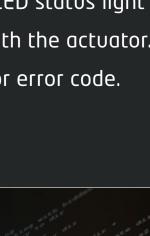


Connect Gluon

ECB

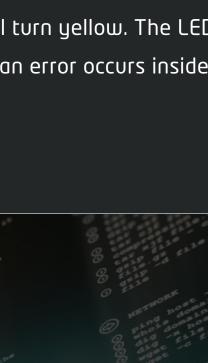






Connect ECB to

computer by RJ45 port



Switch on

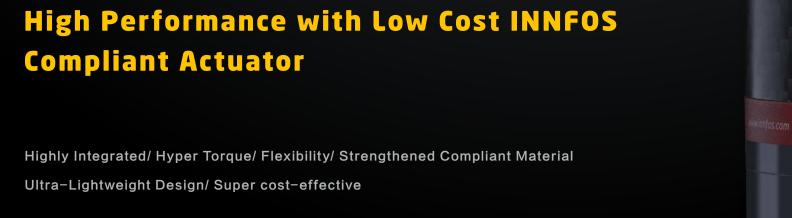
**INNFOS SCA** 

1 Substring INNFOS offers SDK, IAS and IRS for users. SDK provides APIs with various programming languages as well as logging tools for developers to control INNFOS SCA in different environments. IAS(INNFOS Actuator Studio) is a visual debug control software featuring control, ID modification, and visual graphic data regulation.IRS is an INNFOS robotic arm operation software that integrates trajectory planning and teaching programming which makes users can program according to specific application scenarios and op-

erate the robot arm flexibly.

-019.80351 a INVFOS<sup>®</sup>

Linux Windows 10



INNFOS QDD Lite-NE30

35mm **52mm** 

52mm

Output View

**Working Parameters** 

Nominal Voltage: 42VDC

No Load Speed: 167RPM

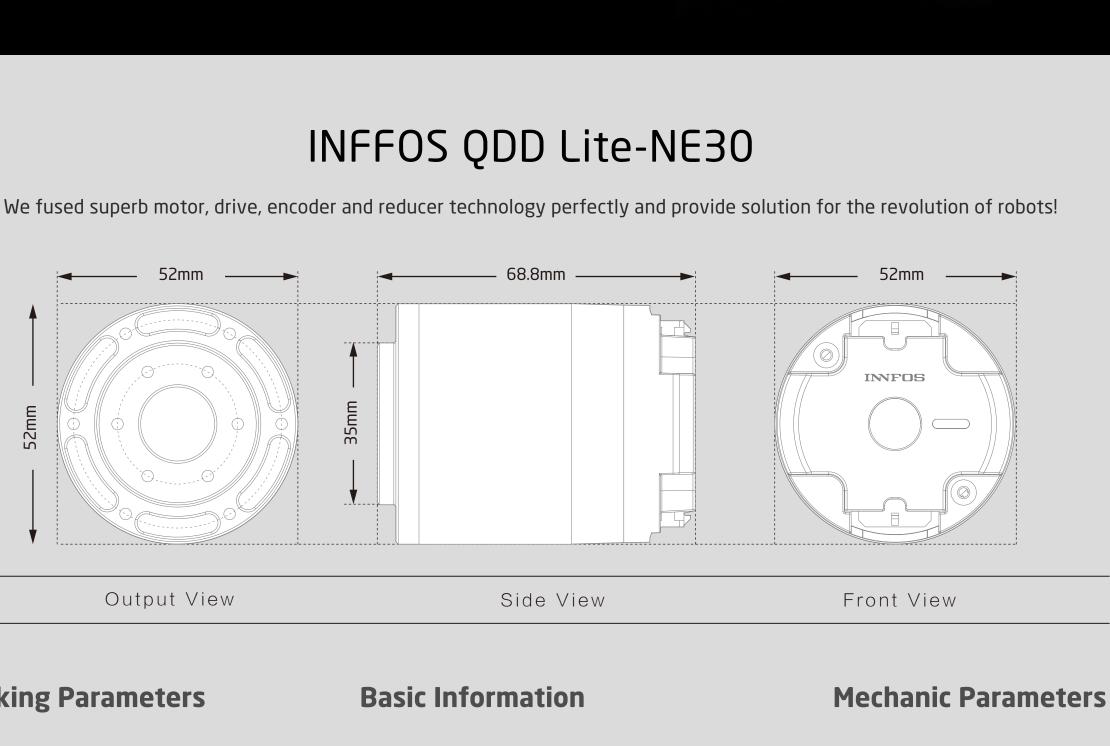
Nominal Speed: 56RPM

Nominal Torque: 2.3Nm

Torque Coefficient: 1.2545Nm/A

Peak Torque: 10Nm

Power: 75W



INFOS

#### Motor Type: Brushless Servo Motor Voltage Range: 24~45VDC Reduction Ratio: 36: 1

Full Range Phase Current: 16.5A Nominal Bus Current: 4.8A Static Bus Current: 0.08A

#### Resolution: 589824(19bit)Step/turn Sensor : Multi-turn Absolute Encoder Signal Interface: Insulated CAN

**Basic Information** 

68.8mm

Side View

Rotation Range : > 360.0° Temperature Range: 0~+50 °C Noise Level: <=70dB(A) INDIVIDUAL PACKAGING The individual packaging for SCA Lite we designed assures you receive our product in outstanding condition.

# Diameter: 52mm

Length: 68.8mm

Weight: 232.1g

Version: v1.8

Backlash: 18Arc min

Maximum Axial Load: 600N

Maximum Radial Load: 900N

